

# From Hamiltonian particle systems to Kinetic equations

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Università di Roma, La Sapienza

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- 1 Particle systems and BBKGY hierarchy (the paradigm of the Kinetic Theory)

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- 7 The Landau equations: grazing collision limit
- 8 The Landau equations and weak-coupling limit

# Particle systems and BBKGY hierarchy

$N$  identical particles, unitary mass, in all the space  $\mathbb{R}^3$ .

Configurations in the phase space

$$z_1 \dots z_N = Z_N = (X_N, V_N) = (x_1 \dots x_N, v_1 \dots v_N)$$

$z_i = (x_i, v_i)$  denotes position and velocity of the  $i$ -th particle.

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Two-body interaction  $\varphi : \mathbb{R}^3 \rightarrow \mathbb{R}$ ,  $\varphi$  is spherically symmetric .

$$\begin{cases} \dot{x}_i = v_i, \\ \dot{v}_i = - \sum_{\substack{j=1 \dots N \\ j \neq i}} \nabla \varphi(x_i - x_j) \end{cases}$$

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$N$  is very large. Statistical description.

## Particle systems and BBKGY hierarchy

Probability measure  $W^N(Z_N)dZ_N$  on  $\mathbb{R}^{3N} \times \mathbb{R}^{3N}$

Symmetry:

$$W^N(z_1 \dots z_i \dots z_j \dots z_N) = W^N(z_1 \dots z_j \dots z_i \dots z_N)$$

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The time evolved measure is defined by

$$W^N(Z_N; t) = W^N(\Phi^{-t}(Z_N))$$

$\Phi^t(Z_N)$  the flow with initial datum  $Z_N$ .

An evolution equation for  $W^N(Z_N; t)$ .



# Particle systems and BBKGY hierarchy

$$\partial_t W^N(t) = \mathcal{L}_N W^N(t)$$

# Particle systems and BBKGY hierarchy

$$\partial_t W^N(t) = \mathcal{L}_N W^N(t)$$

$$\begin{aligned} \mathcal{L}_N = & - \sum_{i=1}^N [v_i \cdot \nabla_{x_i} + F_i \cdot \nabla_{v_i}] \\ & - \sum_{i=1}^N (v_i \cdot \nabla_{x_i}) - \sum_{\substack{i,j=1 \\ i < j}}^N F(x_i - x_j) \cdot (\nabla_{v_i} - \nabla_{v_j}) \end{aligned}$$

$$F_i = - \sum_{j:j \neq i} \nabla \varphi(x_i - x_j)$$

## Particle systems and BBKGY hierarchy

We are interested in the limit  $N \rightarrow \infty$ .  $N$  particle description vs one-particle description.

Define the  $j$ -particle marginals

$$f_j^N(Z_j; t) = \int dz_{j+1} \dots dz_N W^N(Z_j, z_{j+1} \dots z_N; t) \quad j = 1 \dots N.$$

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Evolution equation for  $f_j(t)$ .

$$\int dz_{j+1} \dots dz_N (\partial_t + \sum_{i=1}^N v_i \cdot \nabla_{x_i}) W^N(Z_j, z_{j+1} \dots z_N) = (\partial_t + \sum_{i=1}^j v_i \cdot \nabla_{x_i}) f_j^N$$

free term

## Particle systems and BBKGY hierarchy

$$\int dz_{j+1} \dots dz_N \sum_{i=1}^N F_i \cdot \nabla_{v_i} W^N(Z_j, z_{j+1} \dots z_N) =$$
$$- \sum_{i=1}^N \sum_{k=1, k \neq i}^N \int dz_{j+1} \dots dz_N \nabla_{x_i} \varphi(x_i - x_k) \cdot \nabla_{v_i} W^N(Z_j, z_{j+1} \dots z_N),$$

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$$\sum_{i=j+1}^N \sum_{k=1, k \neq i}^N \dots = 0 .$$

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$\sum_{i=j+1}^N \sum_{k=1, k \neq i}^N \dots = 0 \cdot \sum_{i=1}^j \sum_{k=1, k \neq i}^j \dots +$  the free term  
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$$\sum_{i=1}^j \sum_{k=j+1}^N \int dz_{j+1} \dots dz_N \nabla_{x_i} \varphi(x_i - x_k) \cdot \nabla_{v_i} W^N(Z_j, z_{j+1} \dots z_N) =$$
$$(N-j) \sum_{i=1}^j \int dz_{j+1} \nabla_{x_i} \varphi(x_i - x_{j+1}) \cdot \nabla_{v_i} f_{j+1}^N(Z_j, z_{j+1}).$$



# Particle systems and BBKGY hierarchy

Conclusion:

$$\partial_t f_j^N(t) = \mathcal{L}_j f_j^N(t) + (N - j) C_{j+1} f_{j+1}^N, \quad j = 1 \dots N$$

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$$C_{j+1} f_{j+1}^N(Z_j) = \sum_{i=1}^j \int dz_{j+1} \nabla_{x_i} \varphi(x_i - x_{j+1}) \cdot \nabla_{v_i} f_{j+1}^N(Z_j, z_{j+1})$$

$j < N$  and  $C_{N+1} = 0$ . For  $j = N$  Liouville eq.n  $f_N^N = W^N$ .  
BBKGY hierarchy.

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Interpretation.

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BBKGY hierarchy.

Interpretation. Apparently not useful: we have in any case to solve Liouville.

# Particle systems and BBKGY hierarchy

However if

$$f_2^N(x_1, v_1, x_2, v_2) = f_1^N(x_1, v_1)f_1^N(x_2, v_2)$$

we get a single nonlinear eq.n. Not true.

However if

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we get a single nonlinear eq.n. Not true. But, if for some reason

$$f_2^N(x_1, v_1, x_2, v_2) \approx f_1^N(x_1, v_1)f_1^N(x_2, v_2),$$

in some limiting situations...

# Boltzmann equation

Boltzmann (1872) looked for an equation for

$$\mu(dz, t) = \frac{1}{N} \sum_{i=1}^N \delta(z - z_i(t)) dz.$$

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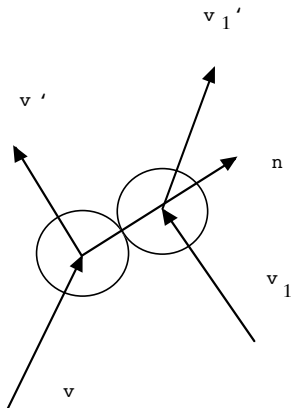
Boltzmann (1872) looked for an equation for

$$\mu(dz, t) = \frac{1}{N} \sum_{i=1}^N \delta(z - z_i(t)) dz.$$

the empirical distribution or for  $f(x, v; t)$ , the one-particle distribution. The dynamics is that of hard spheres.

$$\begin{aligned} v' &= v - n[n \cdot (v - v_1)] \\ v_1' &= v_1 + n[n \cdot (v - v_1)]. \end{aligned}$$

# Boltzmann equation



# Boltzmann equation

The Boltzmann equation

$$(\partial_t + v \cdot \nabla_x) f = Q(f, f)$$

$Q$  is the collision operator

$$Q(f, f)(x, v) = \int_{\mathbb{R}^3} dv_1 \int_{S_+^2} dn \quad (v - v_1) \cdot n \quad [f(x, v') f(x, v'_1) - f(x, v) f(x, v_1)]$$

$n$  (the impact parameter) is a unitary vector and  
 $S_+^2 = \{n \mid n \cdot (v - v_1) \geq 0\}$

# Boltzmann equation

Formal conservation in time of following five quantities

$$\int dx \int dv f(x, v; t) v^\alpha$$

with  $\alpha = 0, 1, 2$ , (conservation of the probability [mass], momentum and energy).

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The entropy defined by

$$H(t) = \int dx \int dv f \log f(x, v, t) \quad (1)$$

is decreasing along the solutions. (The famous H-theorem)  
Equilibrium.

# Boltzmann equation

$\varphi = \varphi(v)$  a test function, consider the scalar product in  $L^2(v)$ :

$$(\varphi, Q(f, f)) = \int dv \int dv_1 \int_{S_+^2} dn \ B(v - v_1; n) \ \varphi[f'f'_1 - ff_1].$$

Here we use the standard notation

$$f = f(v), f' = f(v'), f_1 = f(v_1), f'_1 = f(v'_1).$$

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Here we use the standard notation

$f = f(v)$ ,  $f' = f(v')$ ,  $f_1 = f(v_1)$ ,  $f'_1 = f(v'_1)$ . Using the symmetry  $v \rightarrow v_1$  and the fact that the Jacobian of

$$v, v_1 \rightarrow v', v'_1$$

is unitary,

$$(\varphi, Q(f, f)) = \frac{1}{2} \int dv \int dv_1 \int_{S_+^2} dn \ B(v - v_1; n) \ ff_1[\varphi' + \varphi'_1 - \varphi - \varphi_1]$$

The conservation of mass, momentum and energy follows

$$(\varphi, Q(f, f)) = 0$$

for  $\varphi = 1, v, v^2$ .

# Boltzmann equation

H-theorem is consequence of the identity

$$\dot{H}(t) = (\log f, Q(f, f))$$

$$\varphi = \log f,$$



# Boltzmann equation

H-theorem is consequence of the identity

$$\dot{H}(t) = (\log f, Q(f, f))$$

$\varphi = \log f$ , we arrive to

$$(\log f, Q(f, f)) = \frac{1}{4} \int dx \int dv \int dv_1 \int_{S_+^2} dn \quad B(v - v_1; n) \\ [ff_1 - f'f'_1] \log \frac{f'f'_1}{ff_1}$$

Entropy production.

Boundary conditions.

Paradoxes.

# The hard-sphere dynamics

$N$  identical hard spheres of diameter  $\varepsilon$  of unitary mass.

$$Z_N = (z_1, \dots, z_N) = (X_N, V_N) = (x_1, \dots, x_N; v_1, \dots, v_N)$$

$$z_i = (x_i, v_i) \in \mathbb{R}^6.$$

The phase space

$$\Gamma_N^\varepsilon \subset (\mathbb{R}^6)^N = \{Z_N \mid |x_i - x_j| \geq \varepsilon \text{ for } i \neq j\}$$

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Dynamics is the free flow

$Z_N(t) = (x_1 + v_1 t, \dots, x_N + v_N t; v_1, \dots, v_N)$  up to the first impact time when  $|x_i - x_j| = \varepsilon$ . Then an instantaneous collision takes place, according to the collision law and the flow goes on up to the next collision instant.

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# The hard-sphere dynamics

Symmetric probability measure with density  $W_0^N$  on  $\Gamma_N^\varepsilon$

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Symmetric probability measure with density  $W_0^N$  on  $\Gamma_N^\varepsilon$

$$W^N(Z_N; t) = W_0^N(\Phi^{-t}Z_N).$$

The  $j$ -particle distributions  $f_j^N$  of a measure  $W^N$  (or marginals) are

$$f_j^N(z_1, \dots, z_j; t) = \int dz_{j+1} \dots dz_N \quad W^N(z_1, \dots, z_N; t)$$

Looking for an evolution equation for  $f_j(t)$ .

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Looking for an evolution equation for  $f_j(t)$ . H-S hierarchy.



# H-S hierarchy

For  $Z_N \in \Gamma_N^\varepsilon$

$$\frac{\partial}{\partial t} W^N(Z_N, t) = - \sum_{j=1}^N v_j \cdot \nabla_{x_j} W^N(Z_N, t).$$

# H-S hierarchy

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$$\frac{\partial}{\partial t} W^N(Z_N, t) = - \sum_{j=1}^N v_j \cdot \nabla_{x_j} W^N(Z_N, t).$$

Integrating on the last  $N - 1$  variables:

$$\frac{\partial}{\partial t} f_1(x, v; t) = - \sum_{j=1}^N \int_{\Gamma(x_1)} v_j \cdot \nabla_{x_j} W^N(x_1, v_1 \dots x_N, v_N) dx_2, dv_2 \dots dx_N, dv_N,$$

where

$$\Gamma(x_1) = \{x_2, v_2 \dots x_N, v_N \mid |x_1 - x_s| > \varepsilon, s = 2 \dots N\}.$$

# H-S hierarchy

We deal first with the term  $j = 1$

$$\begin{aligned}v_1 \cdot \nabla_{x_1} f_1(x_1, v_1) &= v_1 \cdot \nabla_{x_1} \int_{\Gamma(x_1)} W^N(x_1, v_1 \dots x_N, v_N) dx_2, dv_2 \dots dx_N, dv_N \\ &= \int_{\Gamma(x_1)} v_1 \cdot \nabla_{x_1} W^N dx_2, dv_2 \dots dx_N, dv_N + \\ &\quad \sum_{s=2}^N \int_{\partial\Gamma_s(x_1)} v_1 \cdot n_s W^N dx_2, dv_2 \dots d\sigma_s, dv_s \dots dx_N, dv_N\end{aligned}$$

$$\partial\Gamma_s(x_1) = \{x_2, v_2 \dots x_N, v_N \mid |x_1 - x_r| > \varepsilon, r = 2 \dots N, r \neq s, |x_1 - x_s| = \varepsilon\}.$$

# H-S hierarchy

By the div lemma:

$$\begin{aligned} & \sum_{j=2}^N \int_{\Gamma(x_1)} v_j \cdot \nabla_{x_j} W^N(x_1, v_1 \dots x_N, v_N) dx_2, dv_2 \dots dx_N, dv_N \\ & \sum_{j=2}^N \int_{\partial\Gamma_j(x_1)} v_j \cdot n_j W^N dx_2, dv_2 \dots d\sigma_j dv_j \dots dx_N, dv_N = \\ & (N-1) \int dv_2 \int d\sigma_2 v_2 \cdot n_2 f_2(x_1, v_1, x_2, v_2) = \\ & (N-1)\varepsilon^2 \int dv_2 \int dnv_2 \cdot nf_2(x_1, v_1, x_1 + \varepsilon n, v_2). \end{aligned}$$

## H-S hierarchy

Using the symmetry of  $W^N$ ,

$$\left(\frac{\partial}{\partial t} + v_1 \cdot \nabla_{x_1}\right) f_1(x_1, v_1; t) = (N-1)\varepsilon^2 \int dv_2 (v_2 - v_1) \cdot n \int dn f_2(x_1, v_1, x_1 + n\varepsilon, v_2)$$

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again not very useful.

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again not very useful. The size of the r.h.s.  $N\varepsilon^3 \approx 10^{-4} \text{cm}^3$ ,  $N\varepsilon^2 = O(1)$

## H-S hierarchy

Using the symmetry of  $W^N$ ,

$$\left(\frac{\partial}{\partial t} + v_1 \cdot \nabla_{x_1}\right) f_1(x_1, v_1; t) = (N-1)\varepsilon^2 \int dv_2 (v_2 - v_1) \cdot n \int dn f_2(x_1, v_1, x_1 + n\varepsilon, v_2)$$

again not very useful. The size of the r.h.s.  $N\varepsilon^3 \approx 10^{-4} \text{cm}^3$ ,  $N\varepsilon^2 = O(1)$  the probability that two tagged particles collide is  $O(\varepsilon^2)$ . The probability that a given particle performs a collision is  $O(N\varepsilon^2) = O(1)$ .

$$f_2(x, v, x_2, v_2) = f_1(x, v) f_1(x_2, v_2)$$

statistical independence may be ok only **before** the collision.



## H-S hierarchy

Applying factorization (propagation of chaos) only for the incoming velocities

$$f_2(x_1, v_1, x_1 + n\varepsilon, v_2) = f_1(x_1, v_1)f_1(x_1 + n\varepsilon, v_2)$$

if  $(v_1 - v_2) \cdot n \geq 0$

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$$f_2(x_1, v_1, x_1 + n\varepsilon, v_2) = f_2(x_1, v'_1, x_1 + n\varepsilon, v'_2)$$

if  $(v_1 - v_2) \cdot n < 0$  (here  $v'_1, v'_2$  are incoming). Changing  $n \rightarrow -n$ ,  $v'_1, v'_2$  are outgoing.

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if  $(v_1 - v_2) \cdot n < 0$  (here  $v'_1, v'_2$  are incoming). Changing  $n \rightarrow -n$ ,  $v'_1, v'_2$  are outgoing. We have the Boltzmann equation. However this can be true only in the limit

$$\varepsilon \rightarrow 0, \quad N \rightarrow \infty, \quad n\varepsilon^2 \rightarrow \text{const.}$$

called Boltzmann-Grad limit.

## H-S hierarchy

In general we have

$$(\partial_t + \mathcal{L}_j^\varepsilon) f_j^N = (N-j)\varepsilon^2 C_{j+1}^\varepsilon f_{j+1}^N, \quad j = 1 \dots N$$

where  $\mathcal{L}_j^\varepsilon$  is the generator of the dynamics of  $j$  hard-spheres of diameter  $\varepsilon$ .

$$C_{j+1}^\varepsilon f_{j+1}^N(x_1, v_1, \dots, x_j, v_j) = - \sum_{k=1}^j \int dn \int dv_{j+1} n \cdot (v_k - v_{j+1})$$
$$f_{j+1}^N(x_1, v_1, \dots, x_k, v_k, \dots, x_k + \varepsilon n, v_{j+1})$$

where  $n$  is the unit vector.

$f_j^N = 0$  if  $j > N$  and hence, for  $j = N$ , we have nothing else than the Liouville equation.

By the previous manipulations:

$$C_{j+1}^\varepsilon f_{j+1}^N(x_1, v_1, \dots, x_j, v_j) = \sum_{k=1}^j \int dv_{j+1} \int_{S^+} dn n \cdot (v_k - v_{j+1})$$
$$f_{j+1}^N(x_1, v_1, \dots, x_k, v'_k, \dots, x_k - \varepsilon n, v'_{j+1})$$
$$- f_{j+1}^N(x_1, v_1, \dots, x_k, v_k, \dots, x_k + \varepsilon n, v_{j+1}) -$$

## H-S hierarchy

$$C_{j+1}^\varepsilon = \sum_{k=1}^j C_{k,j+1}^\varepsilon$$

$$C_{k,j+1}^\varepsilon = C_{k,j+1}^{\varepsilon+} - C_{k,j+1}^{\varepsilon-}$$

and

$$C_{k,j+1}^{\varepsilon+} g_{j+1}(x_1, \dots, x_j; v_1, \dots, v_j) = \int dv_{j+1} \int_{S_+^2} d\omega \omega \cdot (v_k - v_{j+1}) \\ [g_{j+1}(x_1, \dots, x_j, x_k - \varepsilon\omega; v_1, \dots, v'_k, \dots, v'_{j+1})],$$

$$C_{k,j+1}^{\varepsilon-} g_{j+1}(x_1, \dots, x_j; v_1, \dots, v_j) = \int dv_{j+1} \int_{S_+^2} d\omega \omega \cdot (v_k - v_{j+1}) \\ [g_{j+1}(x_1, \dots, x_j, x_k + \varepsilon\omega; v_1, \dots, v_k, \dots, v_{j+1})].$$

## H-S hierarchy

Therefore, by the Dyson (Duhamel) expansion:

$$f_j^\varepsilon(t) = \sum_{n=0}^{N-j} \sum_{\substack{\sigma_1, \dots, \sigma_n \\ \sigma_i = \pm 1}} \sum_{k_1, \dots, k_n} '(-1)^{|\sigma_n|} \int_0^t dt_1 \int_0^{t_1} dt_2 \dots \int_0^{t_{n-1}} dt_n$$

$$\alpha_n^\varepsilon(j) U^\varepsilon(t - t_1) C_{k_1, j+1}^{\varepsilon, \sigma_1} \dots U^\varepsilon(t_{n-1} - t_n) C_{k_n, j+n}^{\varepsilon, \sigma_n} U^\varepsilon(t_n) f_{0, n+j}^\varepsilon.$$

$$\alpha_n^\varepsilon(j) = \varepsilon^{2m} (N-j)(N-j-1) \dots (N-j-n+1).$$



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Here

$$\underline{\sigma}_n = (\sigma_1, \dots, \sigma_n), \quad \sigma_i = \pm 1 \quad |\underline{\sigma}_n| = \sum_j \sigma_j 1$$

and

$$\sum_{k_1, \dots, k_n} ' = \sum_{k_1=1}^j \sum_{k_2=1}^{j+1} \dots \sum_{k_n=1}^{j+n-1}$$