

Low-rank techniques applied to moment equations for the stochastic Darcy problem with lognormal permeability

Francesca Bonizzoni^{1,2} and Fabio Nobile¹

¹CSQI-MATHICSE, EPFL, Switzerland

²MOX, Politecnico di Milano, Italy

Acknowledgments: D. Kressner (EPFL), C. Tobler (EPFL), R. Kumar (RICAM)

Workshop on Partial Differential Equations with Random Coefficients
Berlin, November 13, 2013



Italian project FIRB-IDEAS ('09) *Advanced Numerical Techniques for Uncertainty Quantification in Engineering and Life Science Problems*

Outline

- 1 The lognormal Darcy problem
- 2 Perturbation approach and moment equations
- 3 Approximation properties of the Taylor polynomial
- 4 Moment equations: well posedness and discretization
- 5 Tensor Train approximation
- 6 1D Numerical experiments

Outline

- 1 The lognormal Darcy problem
- 2 Perturbation approach and moment equations
- 3 Approximation properties of the Taylor polynomial
- 4 Moment equations: well posedness and discretization
- 5 Tensor Train approximation
- 6 1D Numerical experiments

Darcy problem with log-normal permeability

We study the groundwater flow in a saturated heterogeneous medium where the permeability is described as a log-normal stochastic r.f. (model widely used in geophysical applications)

$$\begin{cases} -\operatorname{div}(e^{Y(\omega,x)} \nabla u(\omega,x)) = f(x), & \text{a.e. in } D \subset \mathbb{R}^d, \quad d = 1, 2, 3 \\ u(\omega,x) = g(x), & \text{a.e. on } \Gamma_D, \\ e^{Y(\omega,x)} \partial_n u(\omega,x) = h(x), & \text{a.e. on } \Gamma_N. \end{cases}$$

$$Y(\omega,x) : \text{Gaussian r.f.}, \quad \mathbb{E}[Y](x) = \mu(x), \quad \operatorname{Cov}[Y](x,y) = \rho(x,y), \\ \sigma := \left(\frac{1}{|D|} \int_D \rho(x,x) dx \right)^{\frac{1}{2}} < 1.$$

Darcy problem with log-normal permeability

We study the groundwater flow in a saturated heterogeneous medium where the permeability is described as a log-normal stochastic r.f. (model widely used in geophysical applications)

$$\begin{cases} -\operatorname{div}(e^{Y(\omega,x)} \nabla u(\omega,x)) = f(x), & \text{a.e. in } D \subset \mathbb{R}^d, \quad d = 1, 2, 3 \\ u(\omega,x) = g(x), & \text{a.e. on } \Gamma_D, \\ e^{Y(\omega,x)} \partial_n u(\omega,x) = h(x), & \text{a.e. on } \Gamma_N. \end{cases}$$

$$Y(\omega,x) : \text{Gaussian r.f.,} \quad \mathbb{E}[Y](x) = \mu(x), \quad \operatorname{Cov}[Y](x,y) = \rho(x,y), \\ \sigma := \left(\frac{1}{|D|} \int_D \rho(x,x) dx \right)^{\frac{1}{2}} < 1.$$

Assumption: $\operatorname{Cov}[Y] \in \mathcal{C}^{0,t}(\overline{D \times D})$ for some $0 < t \leq 1$.

$$\implies Y \text{ a.s. continuous and } \|Y\|_{L^\infty(D)} \in L^p(\Omega), \quad \forall p \geq 1$$

Darcy problem with log-normal permeability

We study the groundwater flow in a saturated heterogeneous medium where the permeability is described as a log-normal stochastic r.f. (model widely used in geophysical applications)

$$\begin{cases} -\operatorname{div}(e^{Y(\omega,x)} \nabla u(\omega,x)) = f(x), & \text{a.e. in } D \subset \mathbb{R}^d, \quad d = 1, 2, 3 \\ u(\omega,x) = g(x), & \text{a.e. on } \Gamma_D, \\ e^{Y(\omega,x)} \partial_n u(\omega,x) = h(x), & \text{a.e. on } \Gamma_N. \end{cases}$$

$$Y(\omega,x) : \text{Gaussian r.f.,} \quad \mathbb{E}[Y](x) = \mu(x), \quad \operatorname{Cov}[Y](x,y) = \rho(x,y), \\ \sigma := \left(\frac{1}{|D|} \int_D \rho(x,x) dx \right)^{\frac{1}{2}} < 1.$$

Assumption: $\operatorname{Cov}[Y] \in \mathcal{C}^{0,t}(\overline{D \times D})$ for some $0 < t \leq 1$.

$$\implies Y \text{ a.s. continuous and } \|Y\|_{L^\infty(D)} \in L^p(\Omega), \quad \forall p \geq 1$$

Under the above assump. the prb. admits a unique solution

$$u \in L^p(\Omega; H^1(D)), \quad \forall p \geq 1. \quad [\text{Galvis – Sarkis, 2009, Gittelson, 2010, Charrier – Debussche, 2013}]$$

Goal:

Compute statistical quantities for u , i.e. assess how the uncertainty on the permeability reflects on u .

- Expected value $\mathbb{E}[u](x) := \int_{\Omega} u(\omega, x) d\mathbb{P}(\omega)$
- Variance $\mathbb{V}ar[u](x) := \mathbb{E}[u^2](x) - \mathbb{E}[u]^2(x)$
- m -points correlation $\mathbb{E}[u^{\otimes m}](x_1, \dots, x_m) := \mathbb{E}[u(\omega, x_1) \otimes \dots \otimes u(\omega, x_m)]$

Method adopted:

Moment equations

Derive, theoretically analyze and numerically solve the deterministic equations solved by the statistical moments of the stochastic solution

Outline

- 1 The lognormal Darcy problem
- 2 Perturbation approach and moment equations**
- 3 Approximation properties of the Taylor polynomial
- 4 Moment equations: well posedness and discretization
- 5 Tensor Train approximation
- 6 1D Numerical experiments

Perturbation approach and moment equations

(see e.g. [Hydrology literature](#): [Tartakovsky – Neuman, 2008], [Riva – Guadagnini – De Simoni, 2006], [Math. literature](#): [von Petersdorff – Schwab, 2006], [Todor PhD, 2005], [Harbrecht – Schneider – Schwab, 2008])

The proposed approach to compute moments of the solution relies on the following **3 steps**:

Perturbation approach and moment equations

(see e.g. [Hydrology literature](#): [Tartakovsky – Neuman, 2008], [Riva – Guadagnini – De Simoni, 2006], [Math. literature](#): [von Petersdorff – Schwab, 2006], [Todor PhD, 2005], [Harbrecht – Schneider – Schwab, 2008])

The proposed approach to compute moments of the solution relies on the following **3 steps**:

Step 1.

Formally write the Taylor polynomial of $u(Y, x)$ w.r.t. Y , centered in $\mathbb{E}[Y]$.

$$u \simeq T^K u(Y, x) = \sum_{k=0}^K \frac{u^k(Y, x)}{k!}, \quad \begin{array}{l} u^k = D^k[\mathbb{E}[Y]](Y, \dots, Y) \\ k\text{-th Gateaux derivative of } u \end{array}$$

Perturbation approach and moment equations

(see e.g. [Hydrology literature](#): [Tartakovsky – Neuman, 2008], [Riva – Guadagnini – De Simoni, 2006], [Math. literature](#): [von Petersdorff – Schwab, 2006], [Todor PhD, 2005], [Harbrecht – Schneider – Schwab, 2008])

The proposed approach to compute moments of the solution relies on the following 3 steps:

Step 1.

Formally write the Taylor polynomial of $u(Y, x)$ w.r.t. Y , centered in $\mathbb{E}[Y]$.

$$u \simeq T^K u(Y, x) = \sum_{k=0}^K \frac{u^k(Y, x)}{k!}, \quad \begin{array}{l} u^k = D^k[\mathbb{E}[Y]](Y, \dots, Y) \\ k\text{-th Gateaux derivative of } u \end{array}$$

- The k -th Gateaux derivative satisfies a recursive problem (for simplicity here $\mathbb{E}[Y] = 0$)

$$\int_D \nabla u^k(x) \cdot \nabla v(x) \, dx = - \sum_{l=1}^k \binom{k}{l} \int_D Y^l(x) \nabla u^{k-l}(x) \cdot \nabla v(x) \, dx$$

Perturbation approach and moment equations

(see e.g. [Hydrology literature](#): [Tartakovsky – Neuman, 2008], [Riva – Guadagnini – De Simoni, 2006], [Math. literature](#): [von Petersdorff – Schwab, 2006], [Todor PhD, 2005], [Harbrecht – Schneider – Schwab, 2008])

The proposed approach to compute moments of the solution relies on the following **3 steps**:

Step 1.

Formally write the Taylor polynomial of $u(Y, x)$ w.r.t. Y , centered in $\mathbb{E}[Y]$.

$$u \simeq T^K u(Y, x) = \sum_{k=0}^K \frac{u^k(Y, x)}{k!}, \quad \begin{array}{l} u^k = D^k[\mathbb{E}[Y]](Y, \dots, Y) \\ k\text{-th Gateaux derivative of } u \end{array}$$

- The k -th Gateaux derivative satisfies a recursive problem (for simplicity here $\mathbb{E}[Y] = 0$)

$$\int_D \nabla u^k(x) \cdot \nabla v(x) \, dx = - \sum_{l=1}^k \binom{k}{l} \int_D Y^l(x) \nabla u^{k-l}(x) \cdot \nabla v(x) \, dx$$

- The derivatives u^k are not directly computable (they are still ∞ -dimensional random fields)

Perturbation approach and moment equations

Step 2.

Approximate the moments of u using the Taylor expansion; e.g. for the first moment:

$$\mathbb{E}[u](x) \simeq \mathbb{E} [T^K u(Y, x)] = \sum_{k=0}^K \frac{\mathbb{E}[u^k](x)}{k!}$$

Perturbation approach and moment equations

Step 2.

Approximate the moments of u using the Taylor expansion; e.g. for the first moment:

$$\mathbb{E}[u](x) \simeq \mathbb{E} [T^K u(Y, x)] = \sum_{k=0}^K \frac{\mathbb{E}[u^k](x)}{k!}$$

- Each correction term $\mathbb{E}[u^k]$ to the mean satisfies the recursion

$$\int_D \nabla \mathbb{E}[u^k](x) \cdot \nabla v(x) \, dx = - \sum_{l=1}^k \binom{k}{l} \int_D \mathbb{E}[Y^l(x) \nabla u^{k-l}(x)] \cdot \nabla v \, dx$$

Perturbation approach and moment equations

Step 2.

Approximate the moments of u using the Taylor expansion; e.g. for the first moment:

$$\mathbb{E}[u](x) \simeq \mathbb{E} [T^K u(Y, x)] = \sum_{k=0}^K \frac{\mathbb{E}[u^k](x)}{k!}$$

- Each correction term $\mathbb{E}[u^k]$ to the mean satisfies the recursion

$$\int_D \nabla \mathbb{E}[u^k](x) \cdot \nabla v(x) \, dx = - \sum_{l=1}^k \binom{k}{l} \int_D \mathbb{E}[Y^l(x) \nabla u^{k-l}(x)] \cdot \nabla v \, dx$$

- Define the $(l+1)$ -points correlation $\mathbb{E} [u^{k-l} \otimes Y^{\otimes l}] : D^{\times(l+1)} \rightarrow \mathbb{R}$

$$\mathbb{E} [u^{k-l} \otimes Y^{\otimes l}] (x_1, \dots, x_{l+1}) = \mathbb{E} [u^{k-l}(x_1) \otimes Y(x_2) \otimes \dots \otimes Y(x_{l+1})]$$

Perturbation approach and moment equations

Step 2.

Approximate the moments of u using the Taylor expansion; e.g. for the first moment:

$$\mathbb{E}[u](x) \simeq \mathbb{E} [T^K u(Y, x)] = \sum_{k=0}^K \frac{\mathbb{E}[u^k](x)}{k!}$$

- Each correction term $\mathbb{E}[u^k]$ to the mean satisfies the recursion

$$\int_D \nabla \mathbb{E}[u^k](x) \cdot \nabla v(x) dx = - \sum_{l=1}^k \binom{k}{l} \int_D \mathbb{E}[Y^l(x) \nabla u^{k-l}(x)] \cdot \nabla v dx$$

- Define the $(l+1)$ -points correlation $\mathbb{E} [u^{k-l} \otimes Y^{\otimes l}] : D^{\times(l+1)} \rightarrow \mathbb{R}$

$$\mathbb{E} [u^{k-l} \otimes Y^{\otimes l}] (x_1, \dots, x_{l+1}) = \mathbb{E} [u^{k-l}(x_1) \otimes Y(x_2) \otimes \dots \otimes Y(x_{l+1})]$$

and evaluate it on the diagonal $(x, \dots, x) \in D^{\times(l+1)}$:

$$\mathbb{E} [\nabla u^{k-l}(x) Y^l(x)] = (\nabla \otimes \text{Id}^{\otimes l}) \mathbb{E} [u^{k-l} \otimes Y^{\otimes l}] (x, \dots, x)$$

Perturbation approach and moment equations

Step 3.

Write the recursion for the $(l + 1)$ -points correlations $\mathbb{E} [u^j \otimes Y^{\otimes l}]$, $j + l \leq k$.

We start from the problem solved by the k -th derivative:

$$\int_D \nabla u^j(x) \cdot \nabla v(x) \, dx = - \sum_{s=1}^j \binom{j}{s} \int_D Y^s(x) \nabla u^{j-s}(x) \cdot \nabla v(x) \, dx$$

Perturbation approach and moment equations

Step 3.

Write the recursion for the $(l + 1)$ -points correlations $\mathbb{E} [u^j \otimes Y^{\otimes l}]$, $j + l \leq k$.

We start from the problem solved by the k -th derivative:

$$\int_D \nabla u^j(x) \cdot \nabla v(x) \, dx = - \sum_{s=1}^j \binom{j}{s} \int_D Y^s(x) \nabla u^{j-s}(x) \cdot \nabla v(x) \, dx$$

$$\text{l.h.s.} = \int_D \nabla u^j(x_1) \cdot \nabla v(x_1) \, dx_1$$

$$\text{r.h.s.} = \int_D Y^s(x_1) \nabla u^{j-s}(x_1) \cdot \nabla v(x_1) \, dx_1$$

Perturbation approach and moment equations

Step 3.

Write the recursion for the $(l + 1)$ -points correlations $\mathbb{E} [u^j \otimes Y^{\otimes l}]$, $j + l \leq k$.

We start from the problem solved by the k -th derivative:

$$\int_D \nabla u^j(x) \cdot \nabla v(x) \, dx = - \sum_{s=1}^j \binom{j}{s} \int_D Y^s(x) \nabla u^{j-s}(x) \cdot \nabla v(x) \, dx$$

$$\text{l.h.s.} = \int_D Y(x_2) \left(\int_D \nabla u^j(x_1) \cdot \nabla v(x_1) \, dx_1 \right) v(x_2) \, dx_2$$

$$\text{r.h.s.} = \int_D Y(x_2) \left(\int_D Y^s(x_1) \nabla u^{j-s}(x_1) \cdot \nabla v(x_1) \, dx_1 \right) v(x_2) \, dx_2$$

Perturbation approach and moment equations

Step 3.

Write the recursion for the $(l+1)$ -points correlations $\mathbb{E} [u^j \otimes Y^{\otimes l}]$, $j+l \leq k$.

We start from the problem solved by the k -th derivative:

$$\int_D \nabla u^j(x) \cdot \nabla v(x) dx = - \sum_{s=1}^j \binom{j}{s} \int_D Y^s(x) \nabla u^{j-s}(x) \cdot \nabla v(x) dx$$

$$\text{l.h.s.} = \int_D Y(x_{l+1}) \cdots \left(\int_D \nabla u^j(x_1) \cdot \nabla v(x_1) dx_1 \right) \cdots v(x_{l+1}) dx_{l+1}$$

$$\text{r.h.s.} = \int_D Y(x_{l+1}) \cdots \left(\int_D Y^s(x_1) \nabla u^{j-s}(x_1) \cdot \nabla v(x_1) dx_1 \right) \cdots v(x_{l+1}) dx_{l+1}$$

Perturbation approach and moment equations

Step 3.

Write the recursion for the $(l+1)$ -points correlations $\mathbb{E} [u^j \otimes Y^{\otimes l}]$, $j+l \leq k$.

We start from the problem solved by the k -th derivative:

$$\int_D \nabla u^j(x) \cdot \nabla v(x) dx = - \sum_{s=1}^j \binom{j}{s} \int_D Y^s(x) \nabla u^{j-s}(x) \cdot \nabla v(x) dx$$

$$\text{l.h.s.} = \mathbb{E} \left[\int_D Y(x_{l+1}) \cdots \left(\int_D \nabla u^j(x_1) \cdot \nabla v(x_1) dx_1 \right) \cdots v(x_{l+1}) dx_{l+1} \right]$$

$$\text{r.h.s.} = \mathbb{E} \left[\int_D Y(x_{l+1}) \cdots \left(\int_D Y^s(x_1) \nabla u^{j-s}(x_1) \cdot \nabla v(x_1) dx_1 \right) \cdots v(x_{l+1}) dx_{l+1} \right]$$

Perturbation approach and moment equations

Step 3.

Write the recursion for the $(l+1)$ -points correlations $\mathbb{E} [u^j \otimes Y^{\otimes l}]$, $j+l \leq k$.

We start from the problem solved by the k -th derivative:

$$\int_D \nabla u^j(x) \cdot \nabla v(x) \, dx = - \sum_{s=1}^j \binom{j}{s} \int_D Y^s(x) \nabla u^{j-s}(x) \cdot \nabla v(x) \, dx$$

$$\text{l.h.s.} = \int_{D \times (l+1)} \mathbb{E} [\nabla u^j(x_1) Y(x_2) \cdots Y(x_{l+1})] \cdot \nabla v(x_1) \cdots v(x_{l+1}) \, dx_1 \cdots dx_{l+1}$$

$$\text{r.h.s.} = \int_{D \times (l+1)} \mathbb{E} [(\nabla u^{j-s} Y^s) \otimes Y^{\otimes l}] \cdot \nabla v(x_1) \cdots v(x_{l+1}) \, dx_1 \cdots dx_{l+1}$$

Perturbation approach and moment equations

Step 3.

Write the recursion for the $(l+1)$ -points correlations $\mathbb{E} [u^j \otimes Y^{\otimes l}]$, $j+l \leq k$.

We start from the problem solved by the k -th derivative:

$$\int_D \nabla u^j(x) \cdot \nabla v(x) dx = - \sum_{s=1}^j \binom{j}{s} \int_D Y^s(x) \nabla u^{j-s}(x) \cdot \nabla v(x) dx$$

$$\text{l.h.s.} = \int_{D \times (l+1)} \nabla \otimes \text{Id}^{\otimes l} \mathbb{E} [u^j \otimes Y^{\otimes l}] \cdot \nabla v(x_1) \cdots v(x_{l+1}) dx_1 \cdots dx_{l+1}$$

$$\text{r.h.s.} = \int_{D \times (l+1)} \text{Tr}_{1:s+1} \mathbb{E} [\nabla u^{j-s} \otimes Y^{\otimes (s+l)}] \cdot \nabla v(x_1) \cdots v(x_{l+1}) dx_1 \cdots dx_{l+1}$$

Perturbation approach and moment equations

Step 3.

$$\int_{D^{\times(l+1)}} \nabla \otimes \text{Id}^{\otimes l} \mathbb{E} [u^j \otimes Y^{\otimes l}] \cdot \nabla \otimes \text{Id}^{\otimes l} v \, dx_1 \dots dx_{l+1}$$

$$= - \sum_{s=1}^j \binom{j}{s} \int_{D^{\times(l+1)}} \text{Tr}_{|1:s+1} \mathbb{E} \left[\nabla u^{j-s} \otimes Y^{\otimes(s+l)} \right] \cdot \nabla \otimes \text{Id}^{\otimes l} v \, dx_1 \dots dx_{l+1}$$

Perturbation approach and moment equations

Step 3.

$$\int_{D^{\times(l+1)}} \nabla \otimes \text{Id}^{\otimes l} \mathbb{E} [u^j \otimes Y^{\otimes l}] \cdot \nabla \otimes \text{Id}^{\otimes l} v \, dx_1 \dots dx_{l+1}$$

$$= - \sum_{s=1}^j \binom{j}{s} \int_{D^{\times(l+1)}} \text{Tr}_{|1:s+1} \mathbb{E} \left[\nabla u^{j-s} \otimes Y^{\otimes(s+l)} \right] \cdot \nabla \otimes \text{Id}^{\otimes l} v \, dx_1 \dots dx_{l+1}$$

- This is a sequence of **deterministic high dimensional problems**.

Perturbation approach and moment equations

Step 3.

$$\begin{aligned} & \int_{D^{\times(l+1)}} \nabla \otimes \text{Id}^{\otimes l} \mathbb{E} [u^j \otimes Y^{\otimes l}] \cdot \nabla \otimes \text{Id}^{\otimes l} v \, dx_1 \dots dx_{l+1} \\ &= - \sum_{s=1}^j \binom{j}{s} \int_{D^{\times(l+1)}} \text{Tr}_{|1:s+1} \mathbb{E} \left[\nabla u^{j-s} \otimes Y^{\otimes(s+l)} \right] \cdot \nabla \otimes \text{Id}^{\otimes l} v \, dx_1 \dots dx_{l+1} \end{aligned}$$

- This is a sequence of **deterministic high dimensional problems**.
- A similar recursion can be written for higher order moments. For instance, the **k -th order correction to the second moment** will involve the computation of all the correlations

$$\mathbb{E}[u^{j_1} \otimes u^{j_2} \otimes Y^{\otimes l}], \quad j_1 + j_2 + l \leq k$$

The structure of the recursion for the first moment

Dim.	$k = 0$	$k = 1$	$k = 2$	
d	u^0	$\mathbb{E}[u^1]$	$\mathbb{E}[u^2]$...
2d	$\mathbb{E}[u^0 \otimes Y]$	$\mathbb{E}[u^1 \otimes Y]$	\ddots	
3d	$\mathbb{E}[u^0 \otimes Y^{\otimes 2}]$	\ddots		
	\vdots			

Recursive,
triangular
structure

The structure of the recursion for the first moment

Dim.	$k = 0$	$k = 1$	$k = 2$	
d	u^0	$\mathbb{E}[u^1]$	$\mathbb{E}[u^2]$...
2d	$\mathbb{E}[u^0 \otimes Y]$	$\mathbb{E}[u^1 \otimes Y]$	\ddots	
3d	$\mathbb{E}[u^0 \otimes Y^{\otimes 2}]$	\ddots		
	\vdots			

Recursive,
triangular
structure

The Algorithm

```

for  $k = 0, \dots, K$ 
  Compute  $\mathbb{E}[u^0 \otimes Y^{\otimes k}]$ 
  for  $j = 1, \dots, k$ 
    Solve the boundary value problem for  $\mathbb{E}[u^j \otimes Y^{\otimes k-j}]$ 
  end
  The result for  $j = k$  is the  $k$ -th order correction  $\mathbb{E}[u^k]$ 
end

```

The structure of the recursion for the first moment

Dim.	$k = 0$	$k = 1$	$k = 2$	
d	u^0	$\mathbb{E}[u^1]$	$\mathbb{E}[u^2]$...
2d	$\mathbb{E}[u^0 \otimes Y]$	$\mathbb{E}[u^1 \otimes Y]$	\ddots	
3d	$\mathbb{E}[u^0 \otimes Y^{\otimes 2}]$	\ddots		
	\vdots			

Recursive,
triangular
structure

for $k = 0, \dots, K$
 Compute $\mathbb{E}[u^0 \otimes Y^{\otimes k}]$
for $j = 1, \dots, k$
 Solve the boundary value problem for $\mathbb{E}[u^j \otimes Y^{\otimes k-j}]$
end
 The result for $j = k$ is the k -th order correction $\mathbb{E}[u^k]$
end

If $\mathbb{E}[Y] = 0$, $\mathbb{E}[Y^{\otimes(2k+1)}] = 0 \forall k$

The Algorithm

A few relevant questions

- 1 The perturbation method relies on Taylor expansion.
 - What is the accuracy of the Taylor approximation?

A few relevant questions

- 1 The perturbation method relies on Taylor expansion.
 - What is the accuracy of the Taylor approximation?
- 2 The k -th order correction to the mean (or higher order moments) can be obtained by solving the recursion for the correlations $\mathbb{E}[u^j \otimes Y^l]$, $j, l \leq k$.
 - Are these problems well posed?
 - What is the smoothness of the correlations functions $\mathbb{E}[u^j \otimes Y^l]$?

A few relevant questions

- 1 The perturbation method relies on Taylor expansion.
 - What is the accuracy of the Taylor approximation?
- 2 The k -th order correction to the mean (or higher order moments) can be obtained by solving the recursion for the correlations $\mathbb{E}[u^j \otimes Y^l]$, $j, l \leq k$.
 - Are these problems well posed?
 - What is the smoothness of the correlations functions $\mathbb{E}[u^j \otimes Y^l]$?
- 3 From the numerical point of view
 - How can we effectively approximate and solve the equations for the correlations $\mathbb{E}[u^j \otimes Y^l]$? (given that they are high dimensional objects)

Outline

- 1 The lognormal Darcy problem
- 2 Perturbation approach and moment equations
- 3 Approximation properties of the Taylor polynomial**
- 4 Moment equations: well posedness and discretization
- 5 Tensor Train approximation
- 6 1D Numerical experiments

Local convergence of the Taylor series

Let Y be a centered Gaussian random field ($\mathbb{E}[Y] = 0$). Consider the following map defined on the Banach space $L^\infty(D)$ with values in $H^1(D)$:

$$\begin{aligned} u &: L^\infty(D) \rightarrow H^1(D) \\ Y &\mapsto u(Y) \end{aligned}$$

and its Taylor polynomial $T^K u = \sum_{k=0}^K \frac{u^k}{k!}$, where $u^k = D^k[0](Y, \dots, Y)$.

Problem: Is the Taylor series $T^K u$ convergent in H^1 -norm for $K \rightarrow +\infty$?

$$\|T^K u\|_{H^1} \leq \sum_{k=0}^K \frac{\|u^k\|_{H^1}}{k!}$$

Local convergence of the Taylor series

Let Y be a centered Gaussian random field ($\mathbb{E}[Y] = 0$). Consider the following map defined on the Banach space $L^\infty(D)$ with values in $H^1(D)$:

$$\begin{aligned} u : L^\infty(D) &\rightarrow H^1(D) \\ Y &\mapsto u(Y) \end{aligned}$$

and its Taylor polynomial $T^K u = \sum_{k=0}^K \frac{u^k}{k!}$, where $u^k = D^k[0](Y, \dots, Y)$.

Problem: Is the Taylor series $T^K u$ convergent in H^1 -norm for $K \rightarrow +\infty$?

$$\|T^K u\|_{H^1} \leq \sum_{k=0}^K \frac{\|u^k\|_{H^1}}{k!} \leq C \sum_{k=0}^K \left(\frac{\|Y\|_{L^\infty}}{\log 2} \right)^k$$

By a recursive argument we prove that $\|u^k\|_{H^1(D)} \leq C \left(\frac{\|Y\|_{L^\infty}}{\log 2} \right)^k k!$ with $C = C(C_P, \|u^0\|_{H^1})$, C_P being the Poincaré constant.

Local convergence of the Taylor series

Let Y be a centered Gaussian random field ($\mathbb{E}[Y] = 0$). Consider the following map defined on the Banach space $L^\infty(D)$ with values in $H^1(D)$:

$$\begin{aligned} u : L^\infty(D) &\rightarrow H^1(D) \\ Y &\mapsto u(Y) \end{aligned}$$

and its Taylor polynomial $T^K u = \sum_{k=0}^K \frac{u^k}{k!}$, where $u^k = D^k[0](Y, \dots, Y)$.

Problem: Is the Taylor series $T^K u$ convergent in H^1 -norm for $K \rightarrow +\infty$?

$$\|T^K u\|_{H^1} \leq \sum_{k=0}^K \frac{\|u^k\|_{H^1}}{k!} \leq \sum_{k=0}^K \left(\frac{\|Y\|_{L^\infty}}{\log 2} \right)^k$$

By a recursive argument we prove that $\|u^k\|_{H^1(D)} \leq C \left(\frac{\|Y\|_{L^\infty}}{\log 2} \right)^k k!$ with $C = C(C_P, \|u^0\|_{H^1})$, C_P being the Poincaré constant.

The Taylor series is convergent $\forall \sigma > 0$ in the disk $B := \{Y \in L^\infty(D) : \|Y\|_{L^\infty} < \log 2\}$

Global conv. of the Taylor series? A counter example

Let $Y(\omega, x) = \xi(\omega)x$, with $\xi \sim \mathcal{N}(0, \sigma^2)$ Gaussian random variable (one-dimensional probability space). Consider the following one-dimensional PDE

$$\begin{cases} -(e^{\xi(\omega)x} u'(\omega, x))' = 0, & \text{a.e. in } [0, 1] \\ u(\omega, 0) = 0, \quad u(\omega, 1) = 1 \end{cases}$$

The exact solution is $u(\xi, x) = \frac{1 - e^{-\xi x}}{1 - e^{-\xi}}$.

Global conv. of the Taylor series? A counter example

Let $Y(\omega, x) = \xi(\omega)x$, with $\xi \sim \mathcal{N}(0, \sigma^2)$ Gaussian random variable (one-dimensional probability space). Consider the following one-dimensional PDE

$$\begin{cases} -(e^{\xi(\omega)x} u'(\omega, x))' = 0, & \text{a.e. in } [0, 1] \\ u(\omega, 0) = 0, \quad u(\omega, 1) = 1 \end{cases}$$

The exact solution is $u(\xi, x) = \frac{1 - e^{-\xi x}}{1 - e^{-\xi}}$.

Observe that:

- On the real axis ($\xi \in \mathbb{R}$), $u(\xi, x)$ is analytic as a function of ξ .
- In the complex plane ($\xi \in \mathbb{C}$), $u(\xi, x)$ is not entire. Indeed, it admits countable many poles in $\xi = 2\pi ik$, $k \in \mathbb{Z} \setminus \{0\}$.

Global conv. of the Taylor series? A counter example

Let $Y(\omega, x) = \xi(\omega)x$, with $\xi \sim \mathcal{N}(0, \sigma^2)$ Gaussian random variable (one-dimensional probability space). Consider the following one-dimensional PDE

$$\begin{cases} -(e^{\xi(\omega)x} u'(\omega, x))' = 0, & \text{a.e. in } [0, 1] \\ u(\omega, 0) = 0, \quad u(\omega, 1) = 1 \end{cases}$$

The exact solution is $u(\xi, x) = \frac{1 - e^{-\xi x}}{1 - e^{-\xi}}$.

Observe that:

- On the real axis ($\xi \in \mathbb{R}$), $u(\xi, x)$ is analytic as a function of ξ .
- In the complex plane ($\xi \in \mathbb{C}$), $u(\xi, x)$ is not entire. Indeed, it admits countable many poles in $\xi = 2\pi ik$, $k \in \mathbb{Z} \setminus \{0\}$.

The Taylor series centered in $\xi = 0$ converges only in the disk of radius $r < 2\pi$ and $\sum_{K \geq 0} \mathbb{E} [T^K u]$ is not convergent to $\mathbb{E} [u]$

A priori error upper bound

Given the counter example, in general we do not expect $\mathbb{E} [T^K u]$ to be convergent to $\mathbb{E} [u]$.

Nevertheless, for σ and K sufficiently small, $\mathbb{E} [T^K u]$ is a good approximation of $\mathbb{E} [u]$. The method we propose can be used even if the Taylor series is not globally convergent.

A priori error upper bound

Given the counter example, in general we do not expect $\mathbb{E} [T^K u]$ to be convergent to $\mathbb{E} [u]$.

Nevertheless, for σ and K sufficiently small, $\mathbb{E} [T^K u]$ is a good approximation of $\mathbb{E} [u]$. The method we propose can be used even if the Taylor series is not globally convergent.

Problem: Let $0 < \sigma < 1$ be fixed. Which is the optimal degree K_{opt}^σ (which depends in σ) of the Taylor polynomial to consider?

A priori error upper bound

Given the counter example, in general we do not expect $\mathbb{E} [T^K u]$ to be convergent to $\mathbb{E} [u]$.

Nevertheless, for σ and K sufficiently small, $\mathbb{E} [T^K u]$ is a good approximation of $\mathbb{E} [u]$. The method we propose can be used even if the Taylor series is not globally convergent.

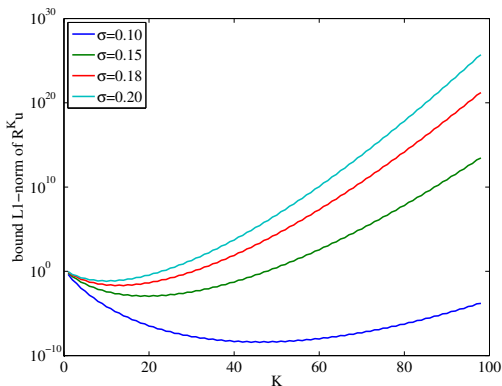
Problem: Let $0 < \sigma < 1$ be fixed. Which is the optimal degree K_{opt}^σ (which depends in σ) of the Taylor polynomial to consider?

A priori error estimate ($0 < \sigma < 1$) [Bonizzoni – Nobile, 2013]

$$\mathbb{E} \|u - T^K u\|_{H^1(D)} \leq C \frac{(K+1)!}{(\log 2)^{K+1}} \sum_{j=K+1}^{\infty} \frac{\sigma^j}{j!!} \leq C \left(\frac{\sigma}{\log 2}\right)^{K+1} K!!$$

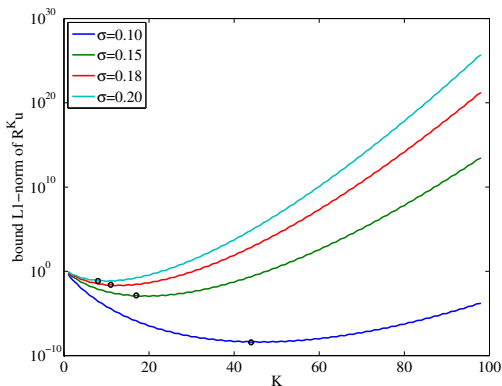
Remark: $K!! = K(K-2)(K-4)\dots 1$

The error upper bound as a function of K



- Divergence of error upper bound $\forall \sigma > 0$

The error upper bound as a function of K



- Divergence of error upper bound $\forall \sigma > 0$
- Estimated “optimal” K , $K_{opt}^\sigma = \left\lfloor \left(\frac{\log 2}{\sigma} \right)^2 \right\rfloor - 4$. (bullets in the picture)

Error upper bound: sketch of the proof

Key ingredients:

- 1 We prove by a recursive argument that

$$\|u^k(tY, x)\|_{H^1(D)} \leq C e^{t\|Y\|_{L^\infty}} \left(\frac{\|Y\|_{L^\infty(D)}}{\log 2} \right)^k k!, \quad 0 \leq t \leq 1$$

- 2 $\mathbb{E} \|Y\|_{L^\infty(D)}^k \leq C \sigma^k(k-1)!!$ (application of a result in [Adler – Taylor, 2007, Charrier – Debussche, 2013]).

Error upper bound: sketch of the proof

Key ingredients:

- 1 We prove by a recursive argument that

$$\|u^k(tY, x)\|_{H^1(D)} \leq C e^{t\|Y\|_{L^\infty}} \left(\frac{\|Y\|_{L^\infty(D)}}{\log 2}\right)^k k!, \quad 0 \leq t \leq 1$$

- 2 $\mathbb{E} \|Y\|_{L^\infty(D)}^k \leq C \sigma^k(k-1)!!$ (application of a result in [Adler – Taylor, 2007, Charrier – Debussche, 2013]).

$$\|u - T^K u\|_{H^1(D)} \leq \frac{1}{K!} \int_0^1 (1-t)^K \|u^{K+1}(tY, x)\|_{H^1(D)} dt$$

Error upper bound: sketch of the proof

Key ingredients:

- ① We prove by a recursive argument that

$$\|u^k(tY, x)\|_{H^1(D)} \leq C e^{t\|Y\|_{L^\infty}} \left(\frac{\|Y\|_{L^\infty(D)}}{\log 2}\right)^k k!, \quad 0 \leq t \leq 1$$

- ② $\mathbb{E} \|Y\|_{L^\infty(D)}^k \leq C \sigma^k(k-1)!!$ (application of a result in [Adler – Taylor, 2007, Charrier – Debussche, 2013]).

$$\begin{aligned} \|u - T^K u\|_{H^1(D)} &\leq \frac{1}{K!} \int_0^1 (1-t)^K \|u^{K+1}(tY, x)\|_{H^1(D)} dt \\ &\leq C(K+1) \left(\frac{\|Y\|_{L^\infty}}{\log 2}\right)^{K+1} \int_0^1 (1-t)^K e^{t\|Y\|_{L^\infty}} dt \quad [\text{use (1)}] \end{aligned}$$

Error upper bound: sketch of the proof

Key ingredients:

- ① We prove by a recursive argument that

$$\|u^k(tY, x)\|_{H^1(D)} \leq C e^{t\|Y\|_{L^\infty}} \left(\frac{\|Y\|_{L^\infty(D)}}{\log 2}\right)^k k!, \quad 0 \leq t \leq 1$$

- ② $\mathbb{E} \|Y\|_{L^\infty(D)}^k \leq C \sigma^k(k-1)!!$ (application of a result in [Adler – Taylor, 2007, Charrier – Debussche, 2013]).

$$\begin{aligned} \|u - T^K u\|_{H^1(D)} &\leq \frac{1}{K!} \int_0^1 (1-t)^K \|u^{K+1}(tY, x)\|_{H^1(D)} dt \\ &\leq C(K+1) \left(\frac{\|Y\|_{L^\infty}}{\log 2}\right)^{K+1} \int_0^1 (1-t)^K e^{t\|Y\|_{L^\infty}} dt \end{aligned}$$

Error upper bound: sketch of the proof

Key ingredients:

- ① We prove by a recursive argument that

$$\|u^k(tY, x)\|_{H^1(D)} \leq C e^{t\|Y\|_{L^\infty}} \left(\frac{\|Y\|_{L^\infty(D)}}{\log 2}\right)^k k!, \quad 0 \leq t \leq 1$$

- ② $\mathbb{E} \|Y\|_{L^\infty(D)}^k \leq C \sigma^k(k-1)!!$ (application of a result in [Adler – Taylor, 2007, Charrier – Debussche, 2013]).

$$\begin{aligned} \|u - T^K u\|_{H^1(D)} &\leq \frac{1}{K!} \int_0^1 (1-t)^K \|u^{K+1}(tY, x)\|_{H^1(D)} dt \\ &\leq C(K+1) \left(\frac{\|Y\|_{L^\infty}}{\log 2}\right)^{K+1} \frac{K!}{\|Y\|_{L^\infty}^{K+1}} \sum_{j=K+1}^{\infty} \frac{\|Y\|_{L^\infty}^j}{j!} \end{aligned}$$

Error upper bound: sketch of the proof

Key ingredients:

- ① We prove by a recursive argument that

$$\|u^k(tY, x)\|_{H^1(D)} \leq C e^{t\|Y\|_{L^\infty}} \left(\frac{\|Y\|_{L^\infty(D)}}{\log 2}\right)^k k!, \quad 0 \leq t \leq 1$$

- ② $\mathbb{E} \|Y\|_{L^\infty(D)}^k \leq C \sigma^k (k-1)!!$ (application of a result in [Adler – Taylor, 2007, Charrier – Debussche, 2013]).

$$\begin{aligned} \|u - T^K u\|_{H^1(D)} &\leq \frac{1}{K!} \int_0^1 (1-t)^K \|u^{K+1}(tY, x)\|_{H^1(D)} dt \\ &\leq C(K+1)! \left(\frac{1}{\log 2}\right)^{K+1} \sum_{j=K+1}^{\infty} \frac{\|Y\|_{L^\infty}^j}{j!} \end{aligned}$$

Error upper bound: sketch of the proof

Key ingredients:

- ① We prove by a recursive argument that

$$\|u^k(tY, x)\|_{H^1(D)} \leq C e^{t\|Y\|_{L^\infty}} \left(\frac{\|Y\|_{L^\infty(D)}}{\log 2}\right)^k k!, \quad 0 \leq t \leq 1$$

- ② $\mathbb{E} \|Y\|_{L^\infty(D)}^k \leq C \sigma^k (k-1)!!$ (application of a result in [Adler – Taylor, 2007, Charrier – Debussche, 2013]).

$$\begin{aligned} \|u - T^K u\|_{H^1(D)} &\leq \frac{1}{K!} \int_0^1 (1-t)^K \|u^{K+1}(tY, x)\|_{H^1(D)} dt \\ &\leq C(K+1)! \left(\frac{1}{\log 2}\right)^{K+1} \sum_{j=K+1}^{\infty} \frac{\|Y\|_{L^\infty}^j}{j!} \end{aligned}$$

$$\mathbb{E} \left[\|u - T^K u\|_{H^1(D)} \right] \leq C(K+1)! \left(\frac{1}{\log 2}\right)^{K+1} \sum_{j=K+1}^{\infty} \frac{\mathbb{E} \left[\|Y\|_{L^\infty}^j \right]}{j!}$$

Error upper bound: sketch of the proof

Key ingredients:

- ① We prove by a recursive argument that

$$\|u^k(tY, x)\|_{H^1(D)} \leq C e^{t\|Y\|_{L^\infty}} \left(\frac{\|Y\|_{L^\infty(D)}}{\log 2} \right)^k k!, \quad 0 \leq t \leq 1$$

- ② $\mathbb{E} \|Y\|_{L^\infty(D)}^k \leq C \sigma^k (k-1)!!$ (application of a result in [Adler – Taylor, 2007, Charrier – Debussche, 2013]).

$$\|u - T^K u\|_{H^1(D)} \leq \frac{1}{K!} \int_0^1 (1-t)^K \|u^{K+1}(tY, x)\|_{H^1(D)} dt$$

$$\leq C(K+1)! \left(\frac{1}{\log 2} \right)^{K+1} \sum_{j=K+1}^{\infty} \frac{\|Y\|_{L^\infty}^j}{j!}$$

$$\mathbb{E} \left[\|u - T^K u\|_{H^1(D)} \right] \leq C(K+1)! \left(\frac{1}{\log 2} \right)^{K+1} \sum_{j=K+1}^{\infty} \frac{\mathbb{E} \left[\|Y\|_{L^\infty}^j \right]}{j!}$$

$$\leq C(K+1)! \left(\frac{1}{\log 2} \right)^{K+1} \sum_{j=K+1}^{\infty} \frac{\sigma^j}{j!!} \quad \text{[use (2)]}$$

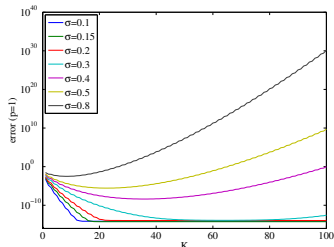
A numerical check: Single Gaussian random variable

$$-\operatorname{div}(e^{\cos(\pi x)\xi(\omega)}\nabla u(\omega, x)) = x \text{ a.e. in } D = [0, 1]$$

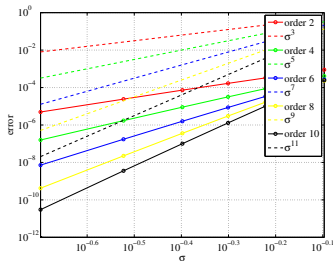
$$\xi(\omega) \sim \mathcal{N}(0, \sigma^2), \quad 0 < \sigma < 1$$

The Taylor polynomial is computable!

Computed error vs K



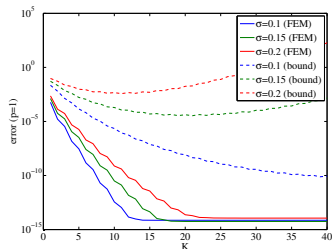
Computed error vs σ



- We numerically show the **divergence of the Taylor series** for any value of the standard deviation $\sigma > 0$
- The **exponential behavior as function of σ** is confirmed

How good is the a priori error estimate?

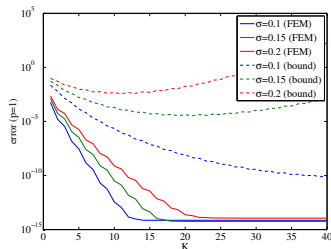
Comp. err. and err. estimate



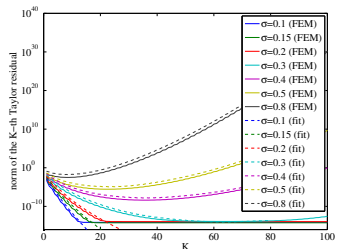
- The a priori error bound is very pessimistic

How good is the a priori error estimate?

Comp. err. and err. estimate



Comp. err. and fitted err. estimate



- The a priori error bound is very pessimistic
- It is possible to fit the parameter γ in the a priori error bound

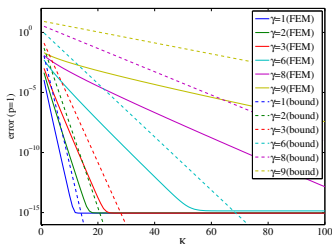
$$\mathbb{E} \|u - T^K u\|_{H^1(D)} \leq C \left(\frac{\gamma \sigma}{\log 2} \right)^{K+1} K!!$$

Single bounded random variable

$$0 < \alpha_1 \leq a(\omega, x) = \mathbb{E}[a](x) + b(x)Y(\omega) \leq \alpha_2 < +\infty$$

$$Y(\omega) \subset [-\gamma, \gamma], \quad 0 < \gamma < +\infty$$

The Taylor series is convergent provided that the variability of a is small enough
 [Babuška – Chatzipantelidis, 2002, Todor PhD, 2005]



Computed error
and bound vs K

Outline

- 1 The lognormal Darcy problem
- 2 Perturbation approach and moment equations
- 3 Approximation properties of the Taylor polynomial
- 4 Moment equations: well posedness and discretization**
- 5 Tensor Train approximation
- 6 1D Numerical experiments

Moment equations: well-posedness and regularity results

Consider again the recursion for the correlations $\mathbb{E}[u^k \otimes Y^{\otimes l}]$:

Dim.	$k = 0$	$k = 1$	$k = 2$	
d	u^0	0	$\mathbb{E}[u^2]$...
2d	0	$\mathbb{E}[u^1 \otimes Y]$...	
3d	$\mathbb{E}[u^0 \otimes Y^{\otimes 2}]$...		
	\vdots			

Theorem: well-posedness [Bonizzoni PhD, 2013]

Let Y be a Gaussian random field with Gaussian covariance function $Cov_Y \in \mathcal{C}^{0,t}(\overline{D \times D})$, $0 < t \leq 1$. Then, **all the problems in the recursion are well-posed.**

Moment equations: well-posedness and regularity results

Consider again the recursion for the correlations $\mathbb{E}[u^k \otimes Y^{\otimes l}]$:

Dim.	$k = 0$	$k = 1$	$k = 2$	
d	u^0	0	$\mathbb{E}[u^2]$...
2d	0	$\mathbb{E}[u^1 \otimes Y]$..	
3d	$\mathbb{E}[u^0 \otimes Y^{\otimes 2}]$..		
	\vdots			

Theorem: well-posedness [Bonizzoni PhD, 2013]

Let Y be a Gaussian random field with Gaussian covariance function $\text{Cov}_Y \in \mathcal{C}^{0,t}(\overline{D \times D})$, $0 < t \leq 1$. Then, **all the problems in the recursion are well-posed.**

Theorem: regularity [Bonizzoni PhD, 2013]

Let Y be a Gaussian random field with Gaussian covariance function $\text{Cov}_Y \in \mathcal{C}^{0,t}(\overline{D \times D})$, $0 < t \leq 1$. Moreover, if the domain is convex and $\mathcal{C}^{1,t/2}$ and $u^0 \in \mathcal{C}^{1,t/2}(\overline{D})$, then $\mathbb{E}[u^k \otimes Y^{\otimes l}] \in \mathcal{C}^{0,t/2,mix}(\overline{D}^{\times l}, \mathcal{C}^{1,t/2}(\overline{D}))$

Problem for $\mathbb{E} [u^1 \otimes Y]$ – Full TP discretization

Given $\mathbb{E} [u^0 \otimes Y^{\otimes 2}] \in H^1(D) \otimes (L^2(D))^{\otimes 2}$, find $\mathbb{E} [u^1 \otimes Y] \in H^1(D) \otimes L^2(D)$ s.t.

$$\int_D \int_D (\nabla \otimes \text{Id}) \mathbb{E} [u^1 \otimes Y] (x_1, x_2) \cdot (\nabla \otimes \text{Id}) v(x_1, x_2) dx_1 dx_2$$

$$= - \int_D \int_D \text{Tr}_{1,2} \mathbb{E} [\nabla u^0 \otimes Y^{\otimes 2}] (x_1, x_2) \cdot (\nabla \otimes \text{Id}) v(x_1, x_2) dx_1 dx_2$$

Problem for $\mathbb{E} [u^1 \otimes Y]$ – Full TP discretization

Given $\mathbb{E} [u^0 \otimes Y^{\otimes 2}] \in H^1(D) \otimes (L^2(D))^{\otimes 2}$, find $\mathbb{E} [u^1 \otimes Y] \in H^1(D) \otimes L^2(D)$ s.t.

$$\int_D \int_D (\nabla \otimes \text{Id}) \mathbb{E} [u^1 \otimes Y] (x_1, x_2) \cdot (\nabla \otimes \text{Id}) v(x_1, x_2) dx_1 dx_2$$

$$= - \int_D \int_D \text{Tr}_{1,2} \mathbb{E} [\nabla u^0 \otimes Y^{\otimes 2}] (x_1, x_2) \cdot (\nabla \otimes \text{Id}) v(x_1, x_2) dx_1 dx_2$$

Let us introduce:

$\{\phi_i\}_i$ linear FEM elements to discretize $H^1(D)$

$\{\psi_j\}_j$ piecewise constants to discretize $L^2(D)$

$$A(n, m) = \int_D \nabla \phi_n(x) \nabla \phi_m(x) dx$$

$$M(i, j) = \int_D \psi_j(x) \psi_i(x) dx$$

$$\mathcal{B}^1(n, i_1, m) = \int_D \nabla \phi_n(x) \psi_{i_1}(x) \nabla \phi_m(x) dx$$

$C_{1,1}(n, i)$ nodal repr. of $\mathbb{E} [u^1 \otimes Y]$

$C_{0,2}(n, i_1, i_2)$ nodal repr. of $\mathbb{E} [u^0 \otimes Y^{\otimes 2}]$

$$A \otimes M C_{1,1} = -\mathcal{B}^1 \otimes M C_{0,2}$$

Problem for $\mathbb{E} [u^1 \otimes Y]$ – Full TP discretization

Given $\mathbb{E} [u^0 \otimes Y^{\otimes 2}] \in H^1(D) \otimes (L^2(D))^{\otimes 2}$, find $\mathbb{E} [u^1 \otimes Y] \in H^1(D) \otimes L^2(D)$ s.t.

$$\int_D \int_D (\nabla \otimes \text{Id}) \mathbb{E} [u^1 \otimes Y] (x_1, x_2) \cdot (\nabla \otimes \text{Id}) v(x_1, x_2) dx_1 dx_2$$

$$= - \int_D \int_D \text{Tr}_{1,2} \mathbb{E} [\nabla u^0 \otimes Y^{\otimes 2}] (x_1, x_2) \cdot (\nabla \otimes \text{Id}) v(x_1, x_2) dx_1 dx_2$$

Let us introduce:

$\{\phi_i\}_i$ linear FEM elements to discretize $H^1(D)$

$\{\psi_j\}_j$ piecewise constants to discretize $L^2(D)$

$$A(n, m) = \int_D \nabla \phi_n(x) \nabla \phi_m(x) dx$$

$$M(i, j) = \int_D \psi_j(x) \psi_i(x) dx$$

$$B^1(n, i_1, m) = \int_D \nabla \phi_n(x) \psi_{i_1}(x) \nabla \phi_m(x) dx$$

$C_{1,1}(n, i)$ nodal repr. of $\mathbb{E} [u^1 \otimes Y]$

$C_{0,2}(n, i_1, i_2)$ nodal repr. of $\mathbb{E} [u^0 \otimes Y^{\otimes 2}]$

$$A \otimes M C_{1,1} = -B^1 \otimes M C_{0,2}$$

Simplifying the mass matrix:

$$A \times_{1:1} C_{1,1} = -B^1 \times_{1:2} C_{0,2}$$

where $\times_{1:s}$ denotes the saturation of the first s indices of both the right and left hand side tensors.

Problem for $\mathbb{E} [u^k \otimes Y^{\otimes l}]$ – Full TP discretization

Generalizing the previous equation:

Tensorial equation

$$A \times_{1:1} C_{k,l} = - \sum_{s=1}^k \binom{k}{s} B^s \times_{1:s+1} C_{k-s,s+l}$$

Problem: Curse of the dimensionality. How to store all the tensors?

Dim.	$k = 0$	$k = 1$	$k = 2$	
$\mathcal{O}(N_h)$	$C_{0,0}$	0	$C_{2,0}$...
$\mathcal{O}(N_h^2)$	0	$C_{1,1}$	\ddots	
$\mathcal{O}(N_h^3)$	$C_{0,2}$	\ddots		
	\vdots			

Outline

- 1 The lognormal Darcy problem
- 2 Perturbation approach and moment equations
- 3 Approximation properties of the Taylor polynomial
- 4 Moment equations: well posedness and discretization
- 5 Tensor Train approximation**
- 6 1D Numerical experiments

Tensor Train (TT) Format [Oseledets, 2011]

Generalization of the SVD decomposition of a matrix in more than 2 dimensions.

SVD of a matrix: let $X \in \mathbb{R}^{N_1 \times N_2}$ be a matrix

$$X(i_1, i_2) = \sum_{\alpha_1=1}^{r_1} G_1(i_1, \alpha_1) G_2(\alpha_1, i_2)$$

Tensor Train (TT) Format [Oseledets, 2011]

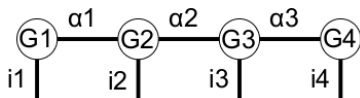
Generalization of the SVD decomposition of a matrix in more than 2 dimensions.

Tensor Train (TT) Format: let $X \in \mathbb{R}^{N_1 \times \dots \times N_n}$ be a tensor of order n

$$X(i_1, \dots, i_n) = \sum_{\alpha_1, \dots, \alpha_{n-1}=1}^{r_1, \dots, r_{n-1}} G_1(i_1, \alpha_1) G_2(\alpha_1, i_2, \alpha_2) \dots G_n(\alpha_{n-1}, i_n)$$

The $(n+1)$ -tuple (r_0, \dots, r_n) is called *TT-rank*

Idea: Storage of **order 3 tensors** in a **(linear) linked format**



Tensor Train (TT) Format [Oseledets, 2011]

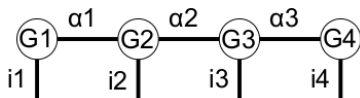
Generalization of the SVD decomposition of a matrix in more than 2 dimensions.

Tensor Train (TT) Format: let $X \in \mathbb{R}^{N_1 \times \dots \times N_n}$ be a tensor of order n

$$X(i_1, \dots, i_n) = \sum_{\alpha_1, \dots, \alpha_{n-1}=1}^{r_1, \dots, r_{n-1}} G_1(i_1, \alpha_1) G_2(\alpha_1, i_2, \alpha_2) \dots G_n(\alpha_{n-1}, i_n)$$

The $(n+1)$ -tuple (r_0, \dots, r_n) is called *TT-rank*

Idea: Storage of **order 3 tensors** in a **(linear) linked format**



- Pro:**
- Storage complexity: $\mathcal{O}(nNr^2)$ vs $\mathcal{O}((N)^n)$, $r = \max r_i$, $N = \max N_i$.
 - It allows fast computations.

Results obtained: Using the Matlab TT-toolbox 2.2 [Oseledets, 2012], we developed a **code which solves the recursive problem for $\mathbb{E}[u]$ in TT-format.**

The TT-algorithm

What does it mean to solve a tensorial equation in TT-format?

$$A \times_{1:1} C_{1,1} = -B^1 \times_{1:2} C_{0,2}$$

$$\Downarrow$$

$$C_{1,1} = -A^{-1} \times_{1:1} (B^1 \times_{1:2} C_{0,2})$$

STEP1

saturation

$B^1 \times_{1:2} C_{0,2}$



STEP2

saturation

with A^{-1}



$$A \times_{1:1} C_{k,l} = - \sum_{s=1}^k \binom{k}{s} B^s \times_{1:s+1} C_{k-s,s+l} \quad (1)$$

Inputs needed:

- TT-format of the correlation $C_{0,s}$, $C_{0,s}^{TT}$, (nodal representation of $\mathbb{E} [u^0 \otimes Y^{\otimes s}]$)
- TT-format of the tensors B^s , $B^{TT,s}$
- Stiffness matrix A

Operations needed:

- Saturation $\times_{1:s}$ between two TT-tensors
- Lin. alg. operations and approximation (tt_round) of tt-tensors [TT-toolbox]

```

for  $k = 0, \dots, K$ 
  Compute  $C_{0,k}^{TT}$  with a tolerance  $tol_{TT}$ 
  for  $l = k - 1, \dots, 0$ 
    Solve the tensorial equation (1)
  end
  The result for  $l = 0$  is the  $k$ -th order correction  $C_{k,0}$ 
end

```

TT-representation of $\mathbb{E} [Y^{\otimes k}]$ [Kumar – Kressner – Nobile – Tobler, 2013]

The starting point is the KL-expansion of the Gaussian random field Y :

$$Y(\omega, x) = \mathbb{E}[Y](x) + \sum_{i=1}^{\infty} \sqrt{\lambda_i} \xi_i(\omega) \phi_i(x), \quad x \in D, \quad \omega \in \Omega$$

where ξ_i i.i.d $\sim \mathcal{N}(0, 1)$ and $\sum_{i=1}^{\infty} \lambda_i = \int_D \text{Var}[Y(x)] dx$.

- k -th correlation:

$$\mathbb{E} [Y^{\otimes k}] (x_1, \dots, x_k) = \sum_{i_1=1}^{\infty} \dots \sum_{i_k=1}^{\infty} \mathbb{E} \left[\prod_{\eta=1}^k \sqrt{\lambda_{i_\eta}} \xi_{i_\eta} \right] \otimes_{\eta=1}^k \phi_{i_\eta}(x_\eta) = \sum_{\mathbf{i} \in \mathbb{N}^k} C_{i_1 \dots i_k} \otimes_{\eta=1}^k \phi_{i_\eta}(x_\eta),$$

where $C_{i_1 \dots i_k} = \prod_{l=1}^{\infty} \lambda_l^{m_l(\mathbf{i})/2} \mathbb{E} [\xi_l^{m_l(\mathbf{i})}]$, $m_l(\mathbf{i})$ = multiplicity of index l in \mathbf{i} .

- $C_{i_1 \dots i_k}$ is supersymmetric.
- An **exact TT symmetric representation** can be constructed:

$$C^{(1, \dots, k/2)} = U_{k/2} M U_{k/2}^T$$

with $U_{k/2}$ basis of $\text{Range}(C^{(1, \dots, k/2)})$.

- Then the basis $C^{(1, \dots, k/2)}$ can be further truncated with a given tolerance tol_{TT} :

$$\|C - \tilde{C}\|_F \leq \text{tol}_{TT}$$

Outline

- 1 The lognormal Darcy problem
- 2 Perturbation approach and moment equations
- 3 Approximation properties of the Taylor polynomial
- 4 Moment equations: well posedness and discretization
- 5 Tensor Train approximation
- 6 1D Numerical experiments**

Test 1 – Analysis of the Taylor approximation

Let $Y(\omega, x)$ be a centered Gaussian r. f. with Gaussian cov. function

$$\text{Cov}_Y(x_1, x_2) = \sigma^2 e^{-\frac{\|x_1 - x_2\|^2}{0.2^2}}, \quad (x_1, x_2) \in [0, 1] \times [0, 1]$$

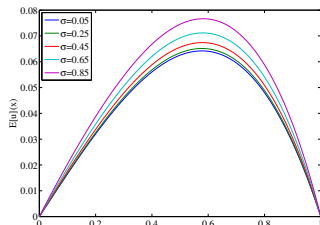
To compute the reference solution and the TT-solution we use:

- same spatial discretization $N_h = 100$ of the physical domain $D = [0, 1]$
- same KL-expansion: $N = 11$ r.v. (99% of variance captured)
- exact TT-computations: $\text{tol}_{TT} = 10^{-16}$

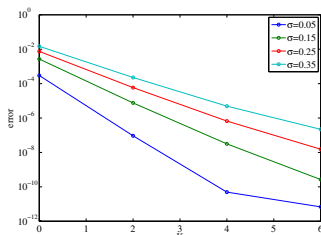


We observe only the truncation error in the Taylor series

Reference solution (collocation)

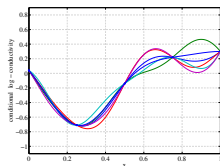


Computed error vs k



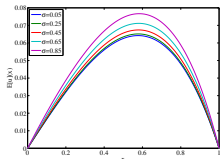
Test 1 – Analysis of the Taylor approx.

- N_{obs} = number of observations of the permeability field
- N = number of random variables considered

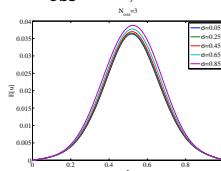


mean
coll.

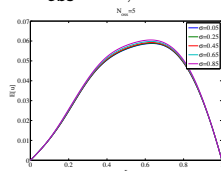
$N_{obs} = 0, N = 11$



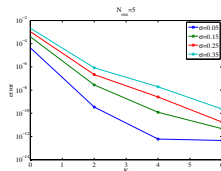
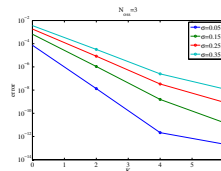
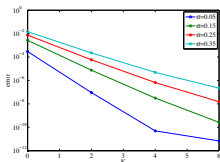
$N_{obs} = 3, N = 9$



$N_{obs} = 5, N = 8$



error
vs K

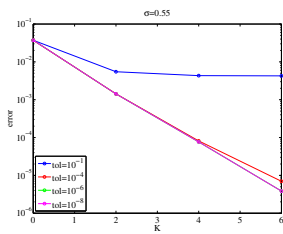
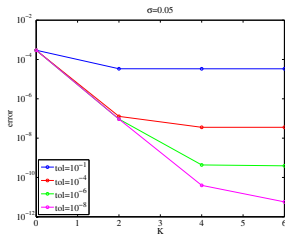
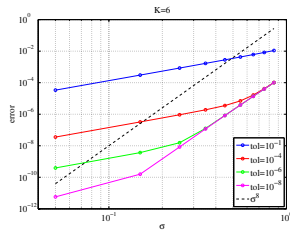
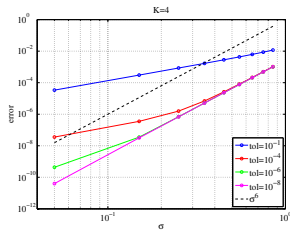
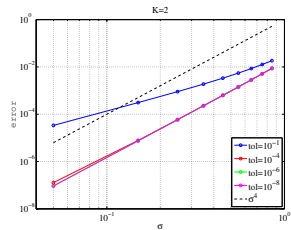


As N_{obs} increases, the variability of the field decreases: good for perturbation methods!

Test 2 – Analysis of the dependence on the TT-precision

Let $Y(\omega, x)$ be a centered Gaussian r. f. with Gaussian cov. function

- same spatial discretization $N_h = 100$ of the physical domain $D = [0, 1]$
- same KL -exp: $N = 26$ r.v. (100% of variance captured up to machine precision)
- different tolerances in the TT-computations

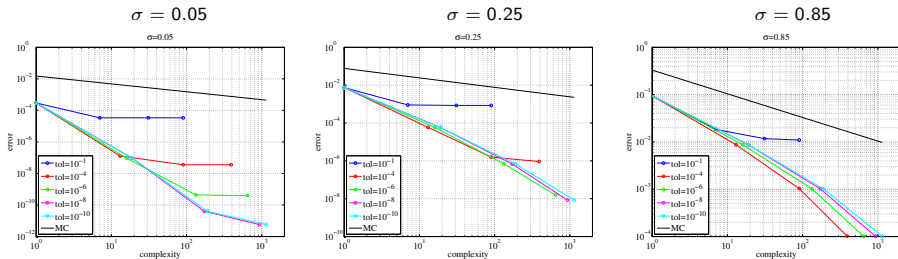


It is not always useful to consider small tol_{TT} .
There is an **optimal tol_{opt}** depending on σ and K

Test 2 – The complexity of the TT-algorithm

Complexity= number of linear systems to be solved

We numerically studied how the error depends on the complexity of the TT-algorithm



error vs complexity for different tol_{TT}

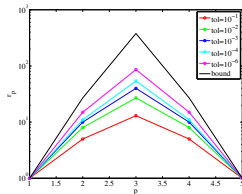
If the optimal tol_{opt} is chosen, the TT-algorithm is far superior to a standard Monte Carlo method (black line)

Test 3 – Storage requirements of the TT-algorithm

Let $Y(\omega, x)$ be a centered Gaussian r. f. with Gaussian cov. function

- spatial discretization $N_h = 200$ of the physical domain $D = [0, 1]$
- exact *KL-exp*: $N = 27$ r.v. (100% of variance captured up to machine precision)
- different tolerances in the TT-computations

TT-ranks of the TT-correlations $\mathcal{C}_{Y^{\otimes k}}^{TT}$ for different tol_{TT}

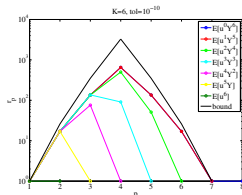


$$r_p \leq \binom{N+p-1}{p}$$

(black line)

[Kumar – Kressner – Nobile – Tobler]

TT-ranks of the correlations in the recursion for $tol_{TT} = 10^{-10}$



the upper bound
(black line) is valid

The storage requirement is a limiting aspect of our algorithm.

Improvements could be obtained thanks to the implementation of sparse TT-tensors



Conclusions

- We have applied the **perturbation technique** to the Darcy problem with lognormal permeability.
- We have studied the **approximation properties of the Taylor polynomial**
- We have derived the **moment equations**, and proved their well-posedness and Hölder-type regularity results.
- We have developed an algorithm in TT-format able to solve the first statistical moment problem. Our TT-algorithm provide a valid solution both in the case where Y is parametrized by a small number of r.v. and if the entire random field is considered.
- If the optimal tol_{TT} is considered, our TT-algorithm is far superior to a standard Monte Carlo method
- The main limitation is the storage requirement.



Adler, R. J. and Taylor, J. E.
Random fields and geometry,
Springer, 2007.



Babuška, I. and Chatzipantelidis, P.
On solving elliptic stochastic partial differential equations,
Comput. Methods Appl. Mech. Engrg., 2002, Vol 191, pp
4093–4122.



Bonizzoni, F.
Analysis and approximation of moment equations for PDEs with
stochastic data,
PhD thesis, Politecnico di Milano, Italy, 2013.



Bonizzoni, F and Nobile, F.
Perturbation analysis for the Darcy problem with log-normal
permeability,
MATHICSE Report 29/2013.



Charrier, J. and Debussche, A.
Weak truncation error estimates for elliptic PDEs with
lognormal coefficients
Stochastic Partial Differential Equations: Analysis and
Computations, 2013, Vol 1, pp 63-93.



Galvis, J. and Sarkis, M.
Approximating infinity-dimensional stochastic Darcy's equations
without uniform ellipticity
SIAM J. Numer. Anal., 2009, Vol 47, pp 3624-3651.



Gittelsohn, C. J.
Stochastic Galerkin discretization of the log-normal isotropic
diffusion problem
Math. Models Methods Appl. Sci., 2010, Vol 20, pp 237–263,



Kumar, R. and Kressner, D. and Nobile, F. and Tobler, C.
Low-rank tensor approximation for high order correlation
functions of Gaussian random fields
In preparation



Harbrecht, H. and Schneider, R. and Schwab, C.
Sparse second moment analysis for elliptic problems in
stochastic domains,
Numerische Mathematik, 2008, Vol 109, pp 385-414.



Oseledets, I. V.
Tensor-train decomposition,
SIAM J. Sci. Comput., 2011, Vol 33, pp 2295–2317.



Riva, M. and Guadagnini, A. and De Simoni, M.
Assessment of uncertainty associated with the estimation of
well catchments by moment equations,
Advances in Water Resources, 2006, Vol 29, 5, pp 676–691.



Tartakovsky, D. M. and Neuman, S. P.
Transient flow in bounded randomly heterogeneous domains: 1.
Exact conditional moment equations and recursive approx,
Water Resour. Res., Vol 34, pp 1–12.



Todor, R. A.
Sparse Perturbation Algorithms for Elliptic PDE's with
Stochastic Data,
PhD thesis, ETH Zurich, Switzerland, 2005.



von Petersdorff, T. and Schwab, C.
Sparse finite element methods for operator equations with
stochastic data
Appl. Math., 2006, Vol 51, pp 145–180.

Thank you for the attention!

Well-posedness of the stochastic Darcy problem

$$\text{find } u \in L^p(\Omega; H^1(D)) \text{ s.t. } u|_{\Gamma_D} = g \text{ a.s., and}$$

$$\int_D a(\omega, x) \nabla_x u(\omega, x) \cdot \nabla_x v(x) \, dx = \int_D f(x) v(x) \, dx \quad \forall v \in H_{\Gamma_D}^1(D), \text{ a.s. in } \Omega.$$

A1 : The permeability field $a \in L^p(\Omega; C^0(\bar{D}))$ for every $p \in (0, \infty)$.

Then, the quantities

$$a_{\min}(\omega) := \min_{x \in \bar{D}} a(\omega, x) \quad (2)$$

$$a_{\max}(\omega) := \max_{x \in \bar{D}} a(\omega, x) \quad (3)$$

are well defined, and $a_{\max} \in L^p(\Omega)$ for every $p \in (0, +\infty)$. Moreover, we assume

A2 : $a_{\min}(\omega) > 0$ a.s., $\frac{1}{a_{\min}(\omega)} \in L^p(\Omega)$ for every $p \in (0, \infty)$.

Theorem

If the permeability field $a(\omega, x)$ satisfies **A1**, **A2**, then the stochastic Darcy problem is well-posed for every $p \in (0, \infty)$, that is it admits a unique solution that depends continuously on the data.

Upper bounds for the statistical moments of $\|Y\|_{L^\infty(D)}$

KL expansion:
$$Y(\omega, x) = \mathbb{E}[Y](x) + \sigma^2 \sum_{j=1}^{+\infty} \sqrt{\tilde{\lambda}_j} \phi_j(x) \xi_j(\omega)$$

① ϕ_j is Hölder continuous with exponent $0 < \gamma \leq 1$ for every $j \geq 1$.

②
$$R_\gamma := \sum_{j=1}^{+\infty} \tilde{\lambda}_j \|\phi_j\|_{C^{0,\gamma}(\bar{D})}^2 < +\infty.$$

Spectral technique [Charrier – Debussche, 2013]

$$\mathbb{E} \left[\|Y'\|_{L^\infty(D)}^k \right] \leq C R_\gamma^{k/2} \sigma^k (k-1)!!, \quad \forall k > 0$$

The domain is a d -dimensional rectangle $D = [0, T]^d$. The centered Gaussian field $Y'(\omega, x)$ is stationary and regular (C^2)

Euler characteristic technique [Adler – Taylor, 2007]

$$\mathbb{E} \left[\|Y'\|_{L^\infty(D)}^k \right] \leq C \sigma^{k-2} k (k-1)!!, \quad \forall k$$

Problem solved by $\mathbb{E} [u^{k-l} \otimes Y^{\otimes l}]$

$$\int_D \dots \int_D \nabla \otimes \text{Id}^{\otimes l} \mathbb{E} [u^{k-l} \otimes Y^{\otimes l}] \cdot \nabla \otimes \text{Id}^{\otimes l} v \, dx_1 \dots dx_{l+1} =$$

$$- \sum_{s=1}^{k-l} \binom{k-l}{s} \int_D \dots \int_D \mathbb{E} [(\nabla u^{k-l-s} Y^s) \otimes Y^{\otimes l}] \cdot \nabla \otimes \text{Id}^{\otimes l} v \, dx_1 \dots dx_{l+1}$$

Hölder spaces with mixed regularity

$\mathcal{C}^{0,\gamma,mix}(\bar{D}^{\times k})$, $0 < \gamma \leq 1$, is the space of all cont. funct. $v : \bar{D}^{\times k} \rightarrow \mathbb{R}$ s.t.

$$|v|_{\mathcal{C}^{0,\gamma,mix}(\bar{D}^{\times k})} := \sup_{\substack{\mathbf{x}, \mathbf{x}+\mathbf{h} \in \bar{D}^{\times k} \\ \mathbf{h} > 0}} \left| D_{\mathbf{h}}^{\gamma,mix} v(x_1, \dots, x_k) \right| < +\infty,$$

where

$$D_{\mathbf{h}}^{\gamma,mix} v(x_1, \dots, x_k) := D_{1,h_1}^{\gamma} \cdots D_{k,h_k}^{\gamma} v(x_1, \dots, x_k),$$

with

$$D_{i,h_i}^{\gamma} v(x_1, \dots, x_k) := \frac{v(x_1, \dots, x_i + h_i, \dots, x_k) - v(x_1, \dots, x_k)}{|h_i|^{\gamma}}.$$

$\mathcal{C}^{0,\gamma,mix}(\bar{D}^{\times k})$ is a Banach space with the norm

$$\|v\|_{\mathcal{C}^{0,\gamma,mix}(\bar{D}^{\times k})} := \|v\|_{\mathcal{C}^0(\bar{D}^{\times k})} + |v|_{\mathcal{C}^{0,\gamma,mix}(\bar{D}^{\times k})}.$$

- $\mathcal{C}^{0,\gamma,mix}(\bar{D}^{\times k}) \subset \mathcal{C}^{0,\gamma}(\bar{D}^{\times k})$
- $\mathcal{C}^{0,\gamma}(\bar{D}^{\times k}) \subset \mathcal{C}^{0,\gamma/k,mix}(\bar{D}^{\times k})$

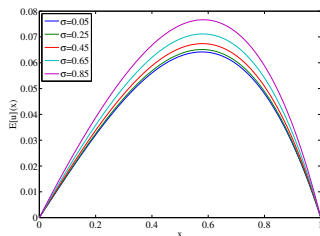
Gaussian cov. function – Truncated KL – error vs σ

Let $Y(\omega, x)$ be a centered Gaussian r. f. with Gaussian cov. function

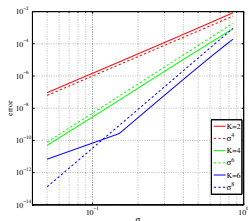
$$\text{Cov}_Y(x_1, x_2) = \sigma^2 e^{-\frac{\|x_1 - x_2\|^2}{0.2^2}}, \quad (x_1, x_2) \in [0, 1] \times [0, 1]$$

- $\text{tol}_{KL} = 10^{-4}$: $N_h = 100$, $N = 11$ r.v. (99% of variance captured)
- $\text{tol}_{TT} = 10^{-16}$

Reference solution (collocation)



Computed error vs σ



Order of $\|\mathbb{E}[u(Y, x)] - \mathbb{E}[T^K u(Y, x)]\|_{L^2(D)}$ as function of σ

	$K = 0$	$K = 1$	$K = 2$	$K = 3$	$K = 4$	$K = 5$	$K = 6$
$\ \mathbb{E}[u - T^K u]\ _{L^2}$	2	2	4	4	6	6	8

Exponential cov. function – Complete KL

Let $Y(\omega, x)$ be a centered Gaussian r. f. with exponential cov. function

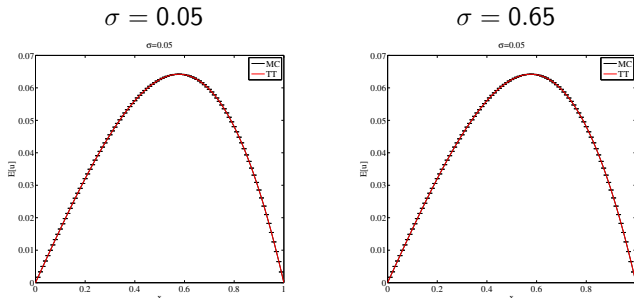
$$\text{Cov}_Y(x_1, x_2) = \sigma^2 e^{-\frac{\|x_1 - x_2\|}{0.2}}, \quad (x_1, x_2) \in [0, 1] \times [0, 1]$$

- $\text{tol}_{KL} = 10^{-4}$: $N_h = 100$, $N = 100$ r.v. (100% of variance captured)
- $\text{tol}_{TT} = 10^{-16}$



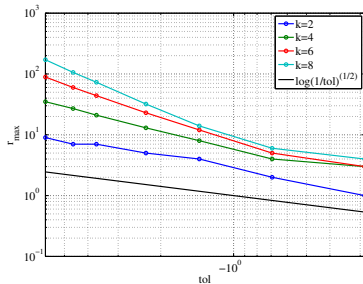
The collocation method is unusable.

We compare the TT-solution with the Monte Carlo solution
($M=10000$ samples)

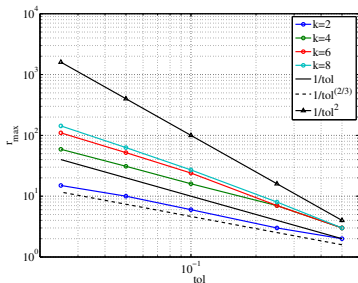


Dependence of the TT-ranks on the dimension

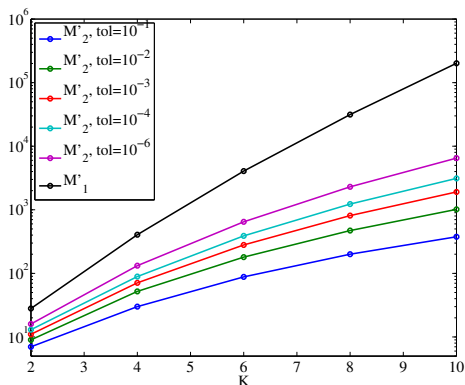
Gauss. Cov. funct.



Esp. Cov. funct.



Comparison with the comp. of a truncated Taylor series



$$\text{Truncated Taylor expansion: } M'_1 = \binom{N + K/2}{K/2}$$

$$\text{TT-algorithm: } M'_2 = \sum_{n=2:2:K} \sum_{p=0}^{n-1} r_p + 1$$